

# A NATURALISED DYNAMICAL ACCOUNT OF COGNITION

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this presentation can be found at: [http://www.barandiaran.net/textos/alergic\\_2004](http://www.barandiaran.net/textos/alergic_2004)

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# OVERVIEW

0. Introduction: the problem, the question
1. Life-as-it-could-be: basic autonomy
2. From life to cognition: the autonomy of the NS
3. Biological Embodiment: more than “just” a physical sensorimotor interface
4. Internal Dynamic Organization: Information is dead, long live to in-formation
5. Naturalizing cognition: recapitulation
6. Postscript: on evolutionary robotics as a theoretical tool (with proposal, ongoing projects and design principles)



**INTRODUCTION**  
the problem:  
*A NATURALISED  
ACCOUNT OF COGNITION*

# Naturalism

## ◆ Ontological:

- Our experience is the result of a unified reality so no specific substances (such as the mental, representations, language, etc.) or *ad hoc* explanations should be admitted to explain it.

## ◆ Methodological:

- Philosophy should go hand by hand with scientific research grounding our understanding of the world on the empirical operations we can inpinge upon it.

## ◆ Note:

- Naturalism should not be judged in itself as a thesis but as a pragmatic proposal evaluated in terms of its achievements...
  - Ultimately naturalism should account for itself through naturalist epistemology, i.e. through the scientific understanding of knowledge itself.

## The question(s)

- ◆ 3 minutes after the Big-Bang there was no cognition and at the scale of  $10^{-20}$  meters there is no cognition...
- ◆ How did cognition arise, how is it sustained?
- ◆ How can we specify cognition as a natural phenomenon which is distinct from those that surround it, underlay it and precede it?
- ◆ How did the fundamental distinction between subject and object of knowledge appear in the history of nature (where no subject or object as such could be found before)?



## Traditional functionalist answer

- ◆ The specificity of cognition is given by the representational nature of the functional input-output relationships of certain systems
- ◆ Representational means:
  - Causal correlation between internal and external states of affairs (Fodor)
  - Evolutionarily selected according to its correlation (Millikan)

## Traditional functionalist answer

- ◆ But:
  - Traditional representationalism presupposes distinction between subject and object of representation
  - Requires an external observer or evolutionary history to ground representational content.
  - The fact that an internal state is a representation of states of affairs in the world does not lie on the causal organization of the system: it is an arbitrary choice of the observer



# Dynamicism (I)

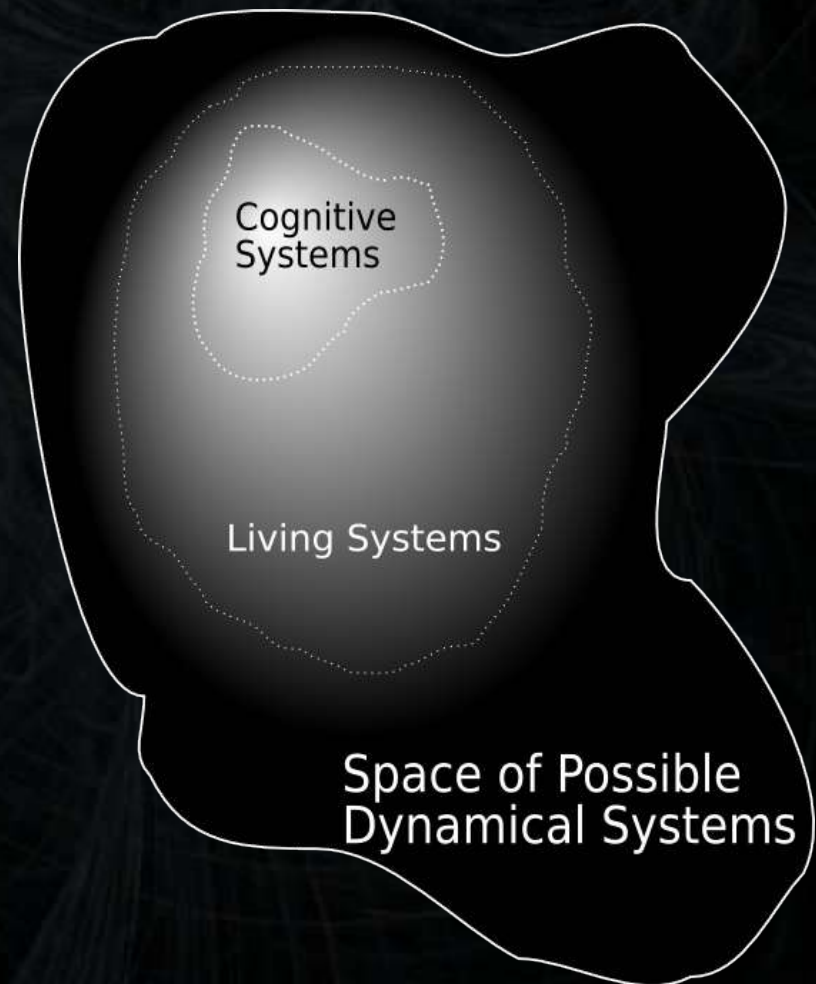
- ◆ The dynamical hypothesis:
  - Ontological: cognitive systems are instances of a dynamical causal organization
  - Methodological: cognitive systems are better understood with dynamical system theory
- ◆ But:
  - Neither the dynamical hypothesis nor DST offers any criteria to distinguish cognitive from non-cognitive dynamical systems.
    - "This paper simply takes an intuitive grasp of the issue for granted. Crudely put, the question here is not what makes something cognitive, but how cognitive agents work " (van Gelder 1998, p.619).
    - But can we understand how cognitive agents work without knowing what makes them cognitive?

## Dynamicism (II)

- ◆ Nonetheless dynamicism:
  1. Allows for modelling of underlying mechanisms
  2. Does not presuppose distinction between mind and world: crosses over brain, body and world.
  3. No compromise with representational theoretical primitives.

# The question reframed

- ◆ From the class of all possible dynamical systems ...
  - Which are the ones we call cognitive?
  - How do we draw the boundaries?
  - If we are not to believe in rigid boundaries still... What specifies the gradient towards the cognitive?
- ◆ We are interested in **cognition-as-it-could-be** independently of particular bio-anatomical structures.





## Naturalistic constraints on the answer

- ◆ The naturalistic approach we defend should be able to account for cognition in two fundamental aspects:
  - **Historic-evolutive**: should account for the diachronic emergence of cognition
  - **Dynamic-organizative**: should account for the synchronic emergence of cognition from the bottom-up,
    - how is cognition sustained and enabled by underlying (more fundamental) processes?
- ◆ The answer should be grounded on the available scientific knowledge and provide productive feedback to science both at empirical-analytic and synthetic (constructive) levels.

# I. BASIC AUTONOMY

*LIFE AS-IT-COULD-BE*

## Bottom-up constraints for any dynamical system (*that could be*)

- ◆ What-can-be is defined by its stability conditions which act by both constraining and enabling the existence of dynamical domains:
  - Persistence of variables and regular interactions between them that we can operationally isolate and measure.
- ◆ Three main kinds of stability in nature:
  - Conservative systems (rocks, atoms, planets): robots and machines in general are conservative systems.
  - Far-from-equilibrium stability (living beings): dissipative structures, thermodynamically open
  - Sequential structures (DNA, replicating templates): require a far-from-equilibrium dynamical system of component production to replicate

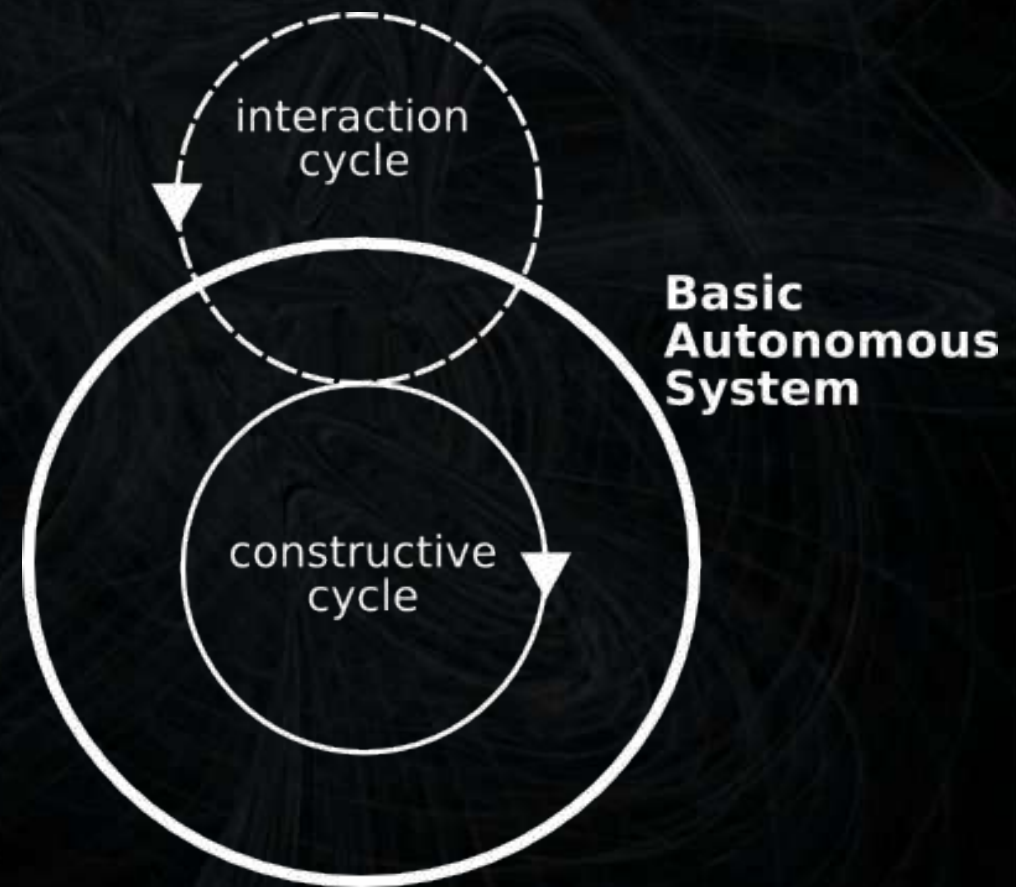


## Basic autonomy

- ◆ **Basic autonomy** (Ruiz-Mirazo & Moreno 2000) is the organization by which:
  - far-from-equilibrium and thermodynamically open systems
  - adaptively generate internal and interactive constraints
  - to modulate the flow of matter and energy required for their self-maintenance.
- ◆ **Similar to autopoiesis but thermodynamically open:**
  - Interactive dynamics are constitutive of the system (structural coupling with the environment is not something that comes additionally but is essential).

# Interaction and construction

- ◆ **Two cycles:**
  - **Constructive:** generation of internal constraints to control the internal flow of matter and energy for self-maintenance (e.g.: metabolism).
  - **Interactive:** control of boundary conditions for self-maintenance (e.g.: active transport through membrane, breathing, adaptive behaviour,...)



# Functionality and normativity

- ◆ **FUNCTIONALITY:** a process is *functional for the system* if it contributes to its self-maintenance
- ◆ **NORMATIVITY:** a process becomes normative if it is dynamically presupposed by other processes in their contribution to the overall self-maintenance.
  - e.g.: the normative (proper, necessary) function of the kidney is to filter blood because the dynamic-metabolic organization of the rest of the organism relies on this blood filtering
- ◆ **NOTE THAT:**
  - No structural decomposition is required.
  - Functional description is not arbitrary (the far-from-equilibrium system) would not exist otherwise.

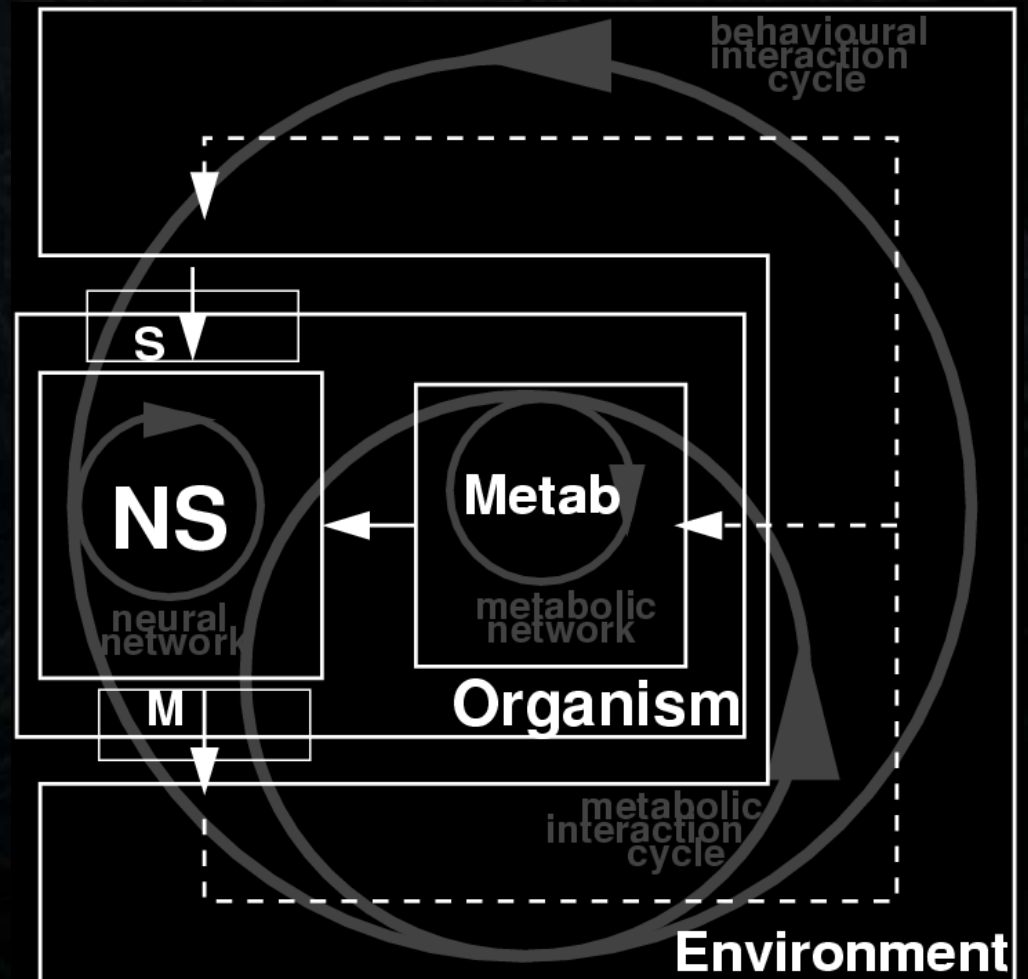


## **II. FROM LIFE TO COGNITION**

*THE AUTONOMY OF THE NERVOUS SYSTEM*

# Decoupling

- ◆ Evolutionarily speaking the appearance of the nervous system (NS) + sensorimotor embodiment implies the decoupling of constructive and interactive cycles
- ◆ Solving a bottleneck between body size and interactive opportunities



# Hierarchical Decoupling

- ◆ Hierarchical Decoupling of the NS from Metabolism:
  - Metabolism generates and sustains a dynamical system (the NS) minimising its local interference with it.
  - Hierarchical: metabolism produces and maintains the architecture of the NS.
  - Decoupling: metabolism underdetermines the activity of the NS (which depends on its internal dynamics and its embodied SM coupling with the environment).
- ◆ Operationally:
  - If we are to predict the state of the NS, local states of cell metabolism are not going to be enough: much more important are the electrochemical states of other neurons and the SM-coupling with the environment.



## Operational dynamical primitives

- ◆ The NS will, in turn, have to be coupled to the global metabolic needs of the organism.
- ◆ But the hierarchical decoupling will allow us to specify the operational primitives (dynamical variables) that constitute this domain, mainly:
  1. change of membrane action potential over time (spikes),
  2. synaptic connections (connectivity matrix) and
  3. modulators: synaptic (local and global) and threshold.
- ◆ The research for these dynamical primitives and its functional higher level organization constitutes the search for a neural “code”: what kind of local differences can make a global difference (spikes, rates, gas-nets, etc.).

# Behavioural Adaptive Autonomy

- ◆ The function of the NS in the overall organization of the organism is behavioural adaptivity, dynamically defined as:
  - Homeostatic maintenance of essential variables under viability constraint through the control of the behavioural interactive coupling with the environment
- ◆ Now the question becomes:
  - What is the dynamic organization of the NS and how is it related to behavioral adaptivity?

# Constraints on the dynamics of the NS

- ◆ Two main kinds of external constraint on the NS:
  - Innate constraints (Elman *et al.* 1996):
    - Chronotopic: timing of certain developmental processes
    - Global architectural: global neural pathways, kinds of connectivity, etc.
  - Value constraints:
    - Big perturbations of neural dynamics through specific signals: pain, hunger, pleasure, etc.
- ◆ The complexity of the possible neural dynamics is subdetermined by this constraints
- ◆ The dynamics of the NS enter a process of local self-organization and historical self-determination through interactions with the environment (internal and external)



# Self-organization

- ◆ Self-organization:
  - Local non-linear interactions between components generate a global behaviour which is maintained through a certain number of constraints of which at least one is a product of the global pattern.
    - Global pattern is not instructed from outside
    - Global pattern cannot be reduced to any of the local components
  - Example: CPG (Central Pattern Generator), interaction between neurons on a local circuit generate a robust oscillatory pattern(s)

# The Autonomy of the NS

- ◆ Autonomous systems are dynamical systems defined as a unity by their organization:
  - they produce themselves (their activity is mainly self-determined) and
  - they distinguish themselves from their surroundings

# The Autonomy of the NS

- ◆ The NS (embodied and situated) is an autonomous systems because:
  - **Integrity:** The dynamic and far-from-equilibrium structure of the NS is maintained by:
    - the network of processes itself (cohesively and recursively)
    - a recursive interaction with the environment
  - **Differentiation:** The dynamic structure of the nervous system is distinguished from the interactive dynamics with the environment by its functional integration, i.e.:
    - a complexity asymmetry by which the internal processes are more complex than the interactive ones
    - system identity can be maintained across a different range of sensorimotor couplings



## Autonomy of the NS

- ◆ All the constraints are not self-generated: value and innate constraints are essential but do not completely specify the dynamics of the NS
- ◆ Starting with this innate constraint and through its sensorimotor coupling with metabolism and environment the autonomy of the NS is an open historical process of self-determination
  - We could say that the organism (through the hierarchical decoupling of the NS) generates a dynamical domain of a much higher variability (complexity) than its metabolic and genetic structure can control.
- ◆ The autonomy of the NS is not an absolute term but a gradual *becoming* (unlike Maturana & Varela's notion of operational closure).

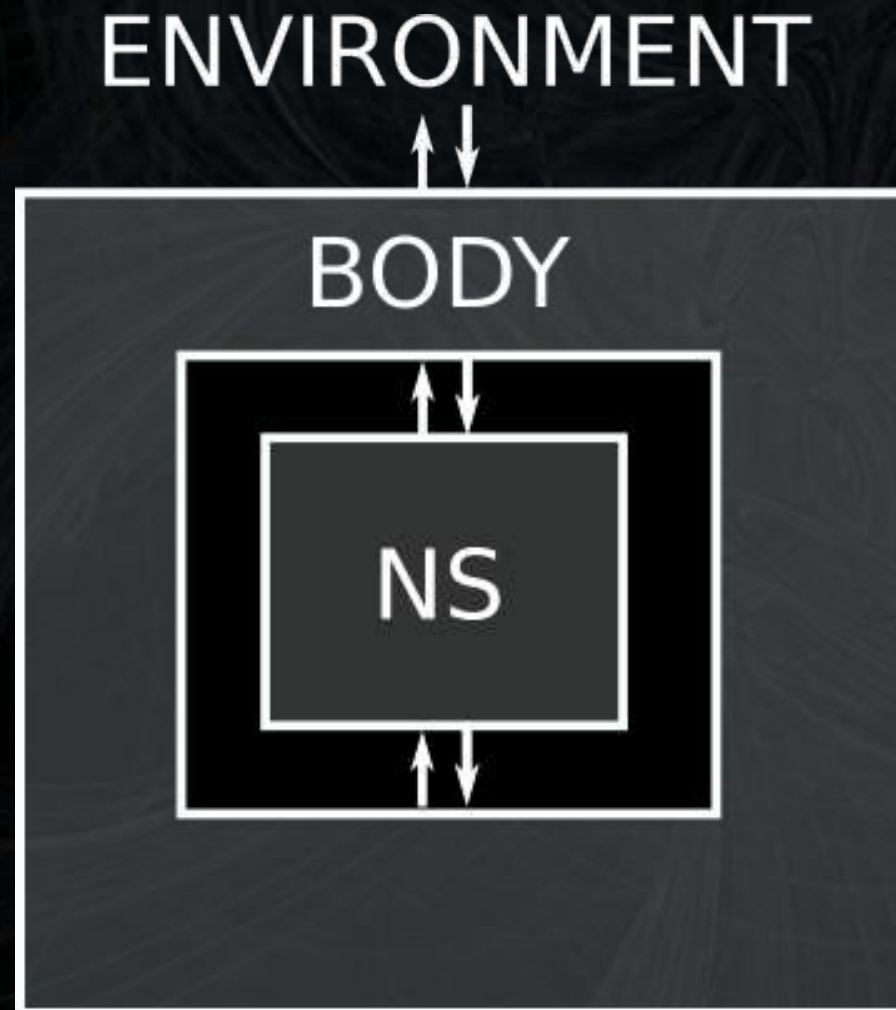
**III. BIOLOGICAL EMBODIMENT**  
*MORE THAN “JUST”*  
*A PHYSICAL SENSORIMOTOR INTERFACE*

## Physical embodiment

- ◆ In the dynamical approach to cognition the body is generally conceptualized as the physical interface between the NS and the environment.
- ◆ Since cognition is the result of closed sensorimotor loops with the environment (not a set of disembodied abstract computations) then body constraints become crucial to the understanding of behaviour.
- ◆ The body becomes like a primary environment for the NS from which the NS cannot decouple (unlike selective engagements with features of the environment).



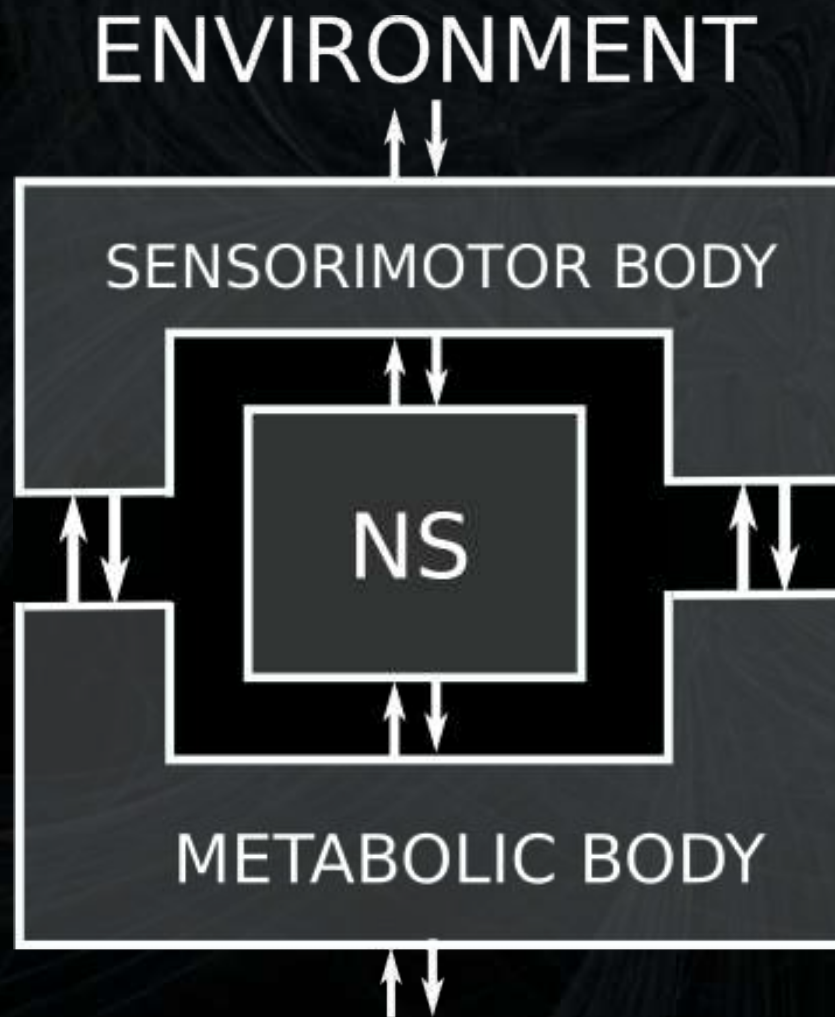
# Physical embodiment



## Biological embodiment

- ◆ The body of the NS is not “just” a physical interface, the (organismic) body, is first of all a biological autonomous (self-sustaining) body.
  - the condition of possibility of the NS as a dynamical system.
- ◆ The brain is not just coupled with the environment through the body but also with the body's internal homeostatic dynamics.
- ◆ Antonio Damasio: the NS interacts with the environment in terms of the effect of this sensorimotor interactions on the (metabolic) body dynamics.
  - somatic markers
  - internal body landscape

# Biological embodiment





## Autonomic NS

- ◆ Organisms whose adaptive strategies rely on motility (fast displacement) are very constrained in size
- ◆ Evolutionary solutions to this problem are vertebrates with endoskeleton and ANS: neural control of metabolism (breathing, blood flow, etc.) ensure metabolic needs of muscles
- ◆ Body and ANS as a source of value dynamics
- ◆ And finally recruited-for non adaptive sensorimotor evaluation: somatic markers for “higher level cognition” (see the role of emotions in decision making)

# IV. INTERNAL DYNAMIC ORGANIZATION

*INFORMATION IS DEAD...  
LONG LIVE IN-FORMATION!*



# Hypothesis

- ◆ The specificity of cognitive dynamics (what makes it different to other dynamical systems) is given by a particular kind of dynamic organization: in-formation.
- ◆ This kind of dynamic organization should account for:
  - intentional and semantic phenomena and
  - the way in which cognitive agents organize their behaviour generating a “world” out of undifferentiated and neutral surroundings



## Information is dead...

- ◆ Informational accounts of the NS activity rely on statistical measures of stimulus-neural activity correlations (conditional probability of neural activation given stimulus  $X$ )
- ◆ But:
  - this correlation is not accesible to the system (whose only access to the stimulus is the neural activation itself!)
  - this approach does not provide any criteria for a particular kind of internal dynamic organization but just a kind of system-environment relationship for a particular observer
  - this cannot account for system detectable error

## Behaviour -- Structure

- ◆ Some preliminary definitions:
  - **STRUCTURE**: is the subset of internal variables involved in a certain sensorimotor coupling (hyperdescription)
  - **STRUCTURAL STABILITY**: happens when a subset of internal variables remains stable or invariant during that coupling, allowing the structure to operate without interference
  - **STRUCTURAL CHANGE**: in given circumstances (different sensorimotor correlations) the structure can change and the old sensorimotor coupling is lost
- ◆ So structure sustains behaviour but it can be the case that **behaviour sustains structure too** because structural stability might depend on a given SM correlation

## Example 1: homeostatic adaptation

- ◆ Agent performs phototaxis
- ◆ Inversion of sensors disrupts phototactic behaviour
- ◆ Agent's internal dynamics enter unstable region
- ◆ Stabilizes when phototaxis is recovered
- ◆ Behavioural stability depends on structural stability



## Long life to in-formation !

- ◆ **In-formation:** is formation from within of the behavioural coupling organized through the expectancies of the interaction outcomes.
  - **Expectancies:** can be clearly defined as dynamic counterfactuals (conditionals): if a certain interactive condition is not met during or after a certain behavioural coupling the dynamic structure involved in the coupling dissolves
- ◆ The “behaviour sustains structure” bit can be decoupled from immediate SM coupling and become dependent on future SM conditions.

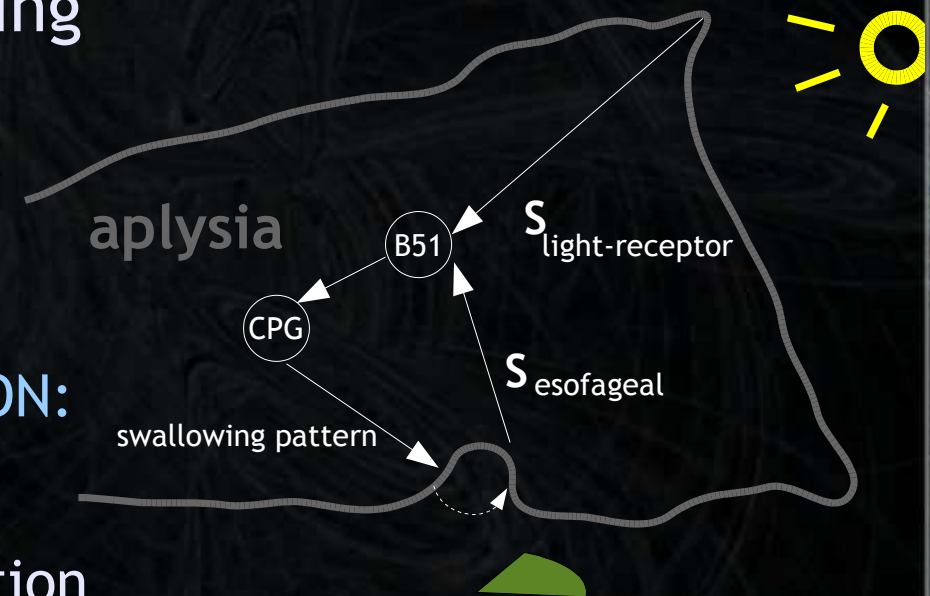
## Example 2: Aplysia

- ♦ Activity of neuron B51, triggered by light receptors, modulates bucal-motor CPG generating swallowing
  - STRUCTURE:  $S_{\text{light}} \rightarrow \text{B51} \rightarrow \text{CPG}$
  - BEHAVIOUR: light-swallowing SM coupling.



## Example 2: Aplysia

- ◆ Activity of neuron B51, triggered by light receptors, modulates bucal-motor CPG generating swallowing
  - STRUCTURE:  $S_{\text{light}} \rightarrow \text{B51} \rightarrow \text{CPG}$
  - BEHAVIOUR: light-swallowing SM coupling.
  - STRUCTURAL STABILITY CONDITION:  $S_{\text{esofageal}} \rightarrow \text{B51}$
  - EXPECTATION: light-food correlation
- ◆ Structural stability depends on satisfaction of expectations





# In-formational dynamic organization

- ◆ Webs of dependencies and transitions can be created between dynamic structures generating an “internal world”
- ◆ **Affordances:** new environmental conditions are “shaped” as possibilities for actions (as a regions of the dynamic structure web)
- ◆ **Goals:** stability condition can be understood as goal states
- ◆ **Developmental autonomy:** the sub-determination of neural dynamics is progressively constrained by the structures stabilized, first through body value signals and then by the already existing dependencies

# In-formational dynamic organization

- ◆ The gradient towards the cognitive is given by
  1. the time span of the expectancies,
  2. reduction of local-context dependencies and
  3. the complexity of the internal (and external?) web of dynamic dependencies

# V. NATURALIZING COGNITION (*RECAPITULATION*)



## Back to the question

- ◆ From the set of all possible dynamical systems what kind of criteria can we offer to distinguish the cognitive from the non-cognitive ones?
- ◆ How can we answer the question with what we have seen so far?
- ◆ I propose 4 main criteria for naturalizing cognition

## 4 criteria for naturalizing cognition (I)

1. **HIERARCHICAL DECOUPLING** (neural dynamics not interefered by local metabolic dynamics) provides domain specificity
2. **BIOLOGICAL EMBODIMENT** (physical-interactive + metabolic) provides enabling constraints and basic (adaptive) functional feedback

## 4 criteria for naturalizing cognition (II)

### 3. AUTONOMY provides identity:

- integrity through recursivity and functional integration
- differentiation from environmental dynamics (agency) through complexity asymmetry

### 4. IN-FORMATIONAL DYNAMIC ORGANIZATION provides dynamic specificity



# A naturalized definition of cognition

- ◆ Cognition is:
  - a dynamic behaviour
  - generated by an autonomous (holistic, integrated and recurrent) dynamical domain (the NS)
  - in-formationally organized and
  - hierachically decoupled but embodied and situated in its material conditions of possibility

**VI. POSTSCRIPT**  
*ON EVOLUTIONARY ROBOTICS  
AS A THEORETICAL TOOL*  
*(with suggestions, projects and examples)*

# Consequences of the 4 criteria for ER (and AI in general)

- ◆ Hierarchical decoupling (domain specificity):
  - Hierarchical decoupling justifies the level of abstraction of ER (the modelling of cognition does not require the modelling of all metabolic and anatomical details)
- ◆ Biological embodiment:
  - Past-emphasis: brain-body coevolution, embodied dynamics, control of perception, etc.
  - Special lack of metabolic embodiment in current ER models,
  - Metabolism-->Brain interaction providing functional feed-back (far-from-equilibrium and system accessible fitness functions)
  - Brain-->Metabolism interaction control of functional homeostatis (e.g. control of energy rate into motors)



# Consequences of the 4 criteria for ER (and AI in general)

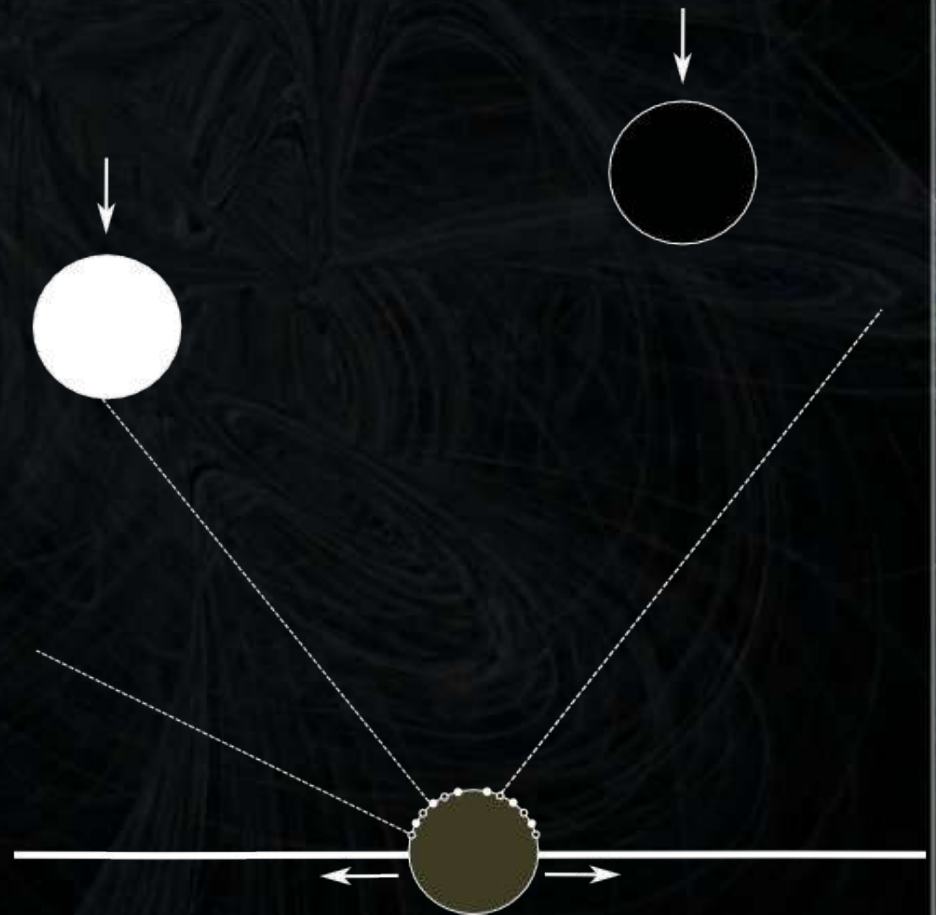
- ◆ **Autonomy (integrity and differentiation):**
  - Synthetically:
    - autonomy is achieved through CTRNNs (recurrency, functional integration, etc.)
    - high environmental variability will force behavioural decoupling from particular agent-environment relationships increasing autonomy
  - Analytically: we could start quantitatively analyzing autonomy with complexity measures
    - recent work by Seth & Edelman (2004) provide interesting analytical tools.

# Consequences of the 4 criteria for ER (and AI in general)

- ◆ In-formational dynamic organization:
  - Synthetically: behaviour coupled with internal stability conditions, this can be achieved in several ways:
    - metabolic embodiment is one of them,
    - homeostatic plasticity is another one
  - Analytically: intermediate explanatory patterns in the system relating dynamic structures with behaviour
    - McGregor & Fernando's definition of hyperdescriptions might be useful here

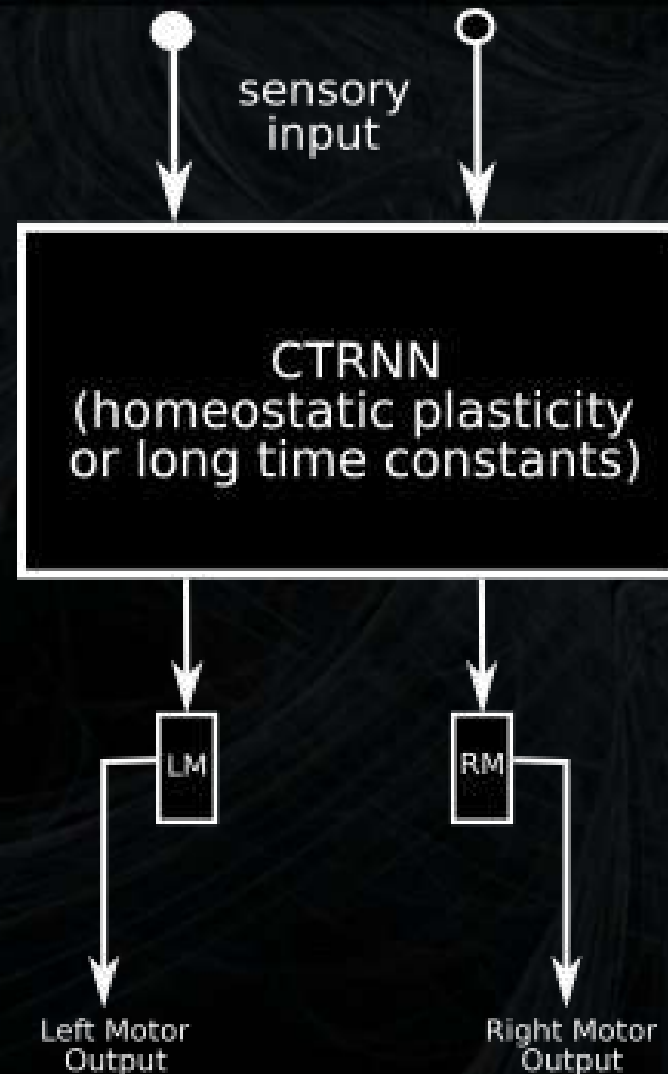
# Experimental Design (I): TASC

- ◆ Two food sources
- ◆ Different food profitability
- ◆ Agent “eats” food
- ◆ Energy based fitness function

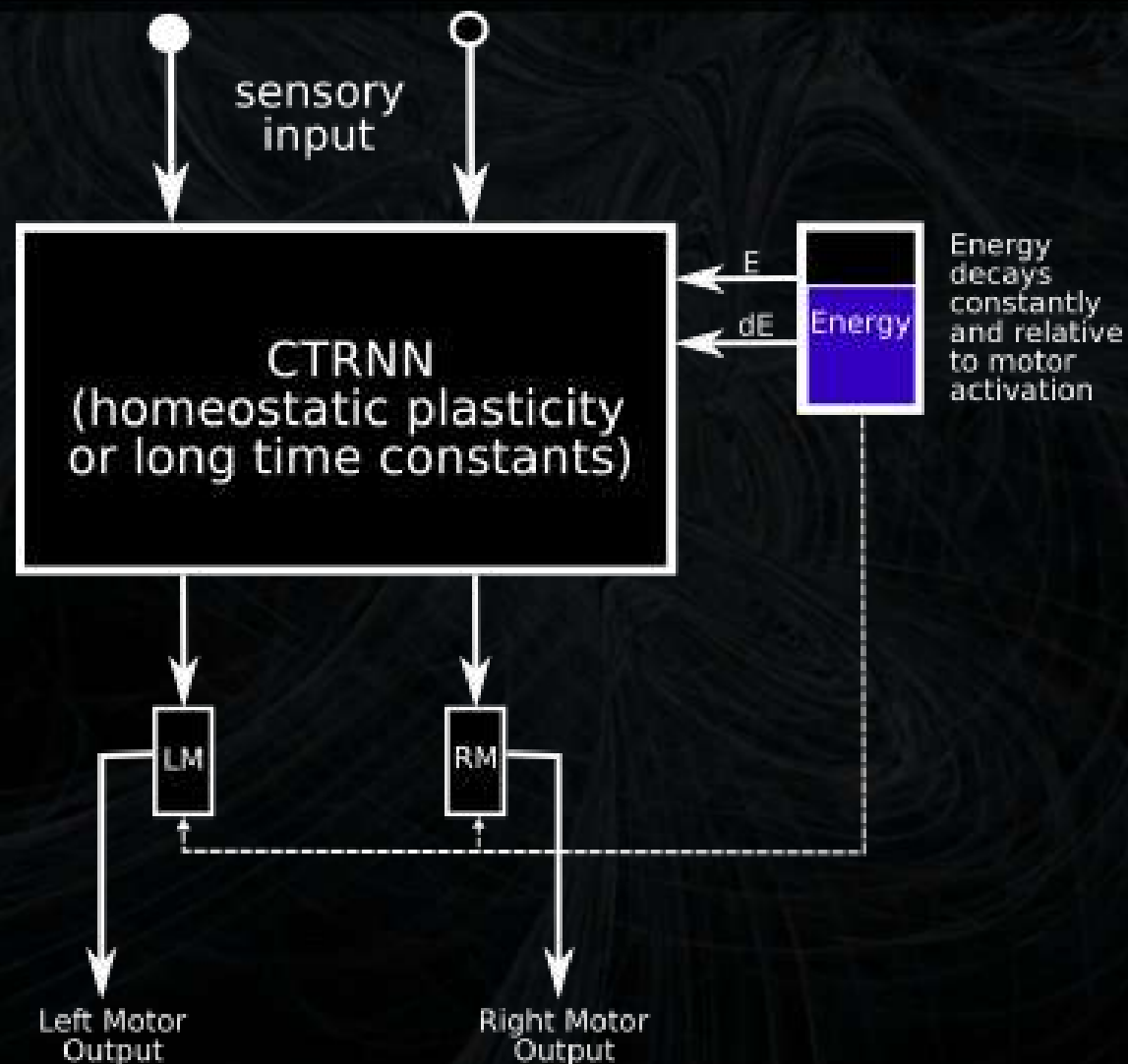




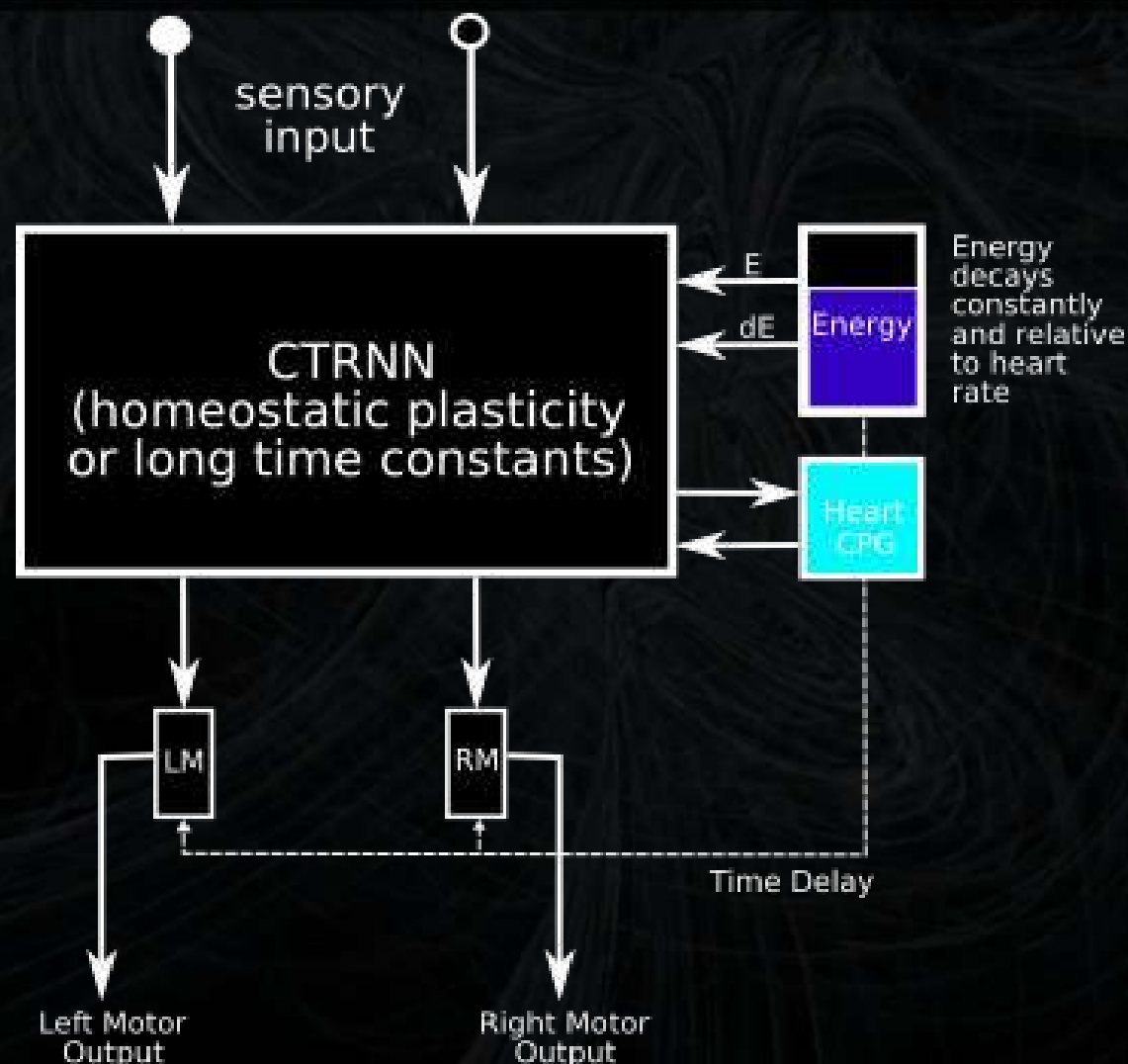
# Experimental Design (II): CONTROL ARCHITECTURE



# Experimental Design (II): CONTROL ARCHITECTURE



# Experimental Design (II): CONTROL ARCHITECTURE

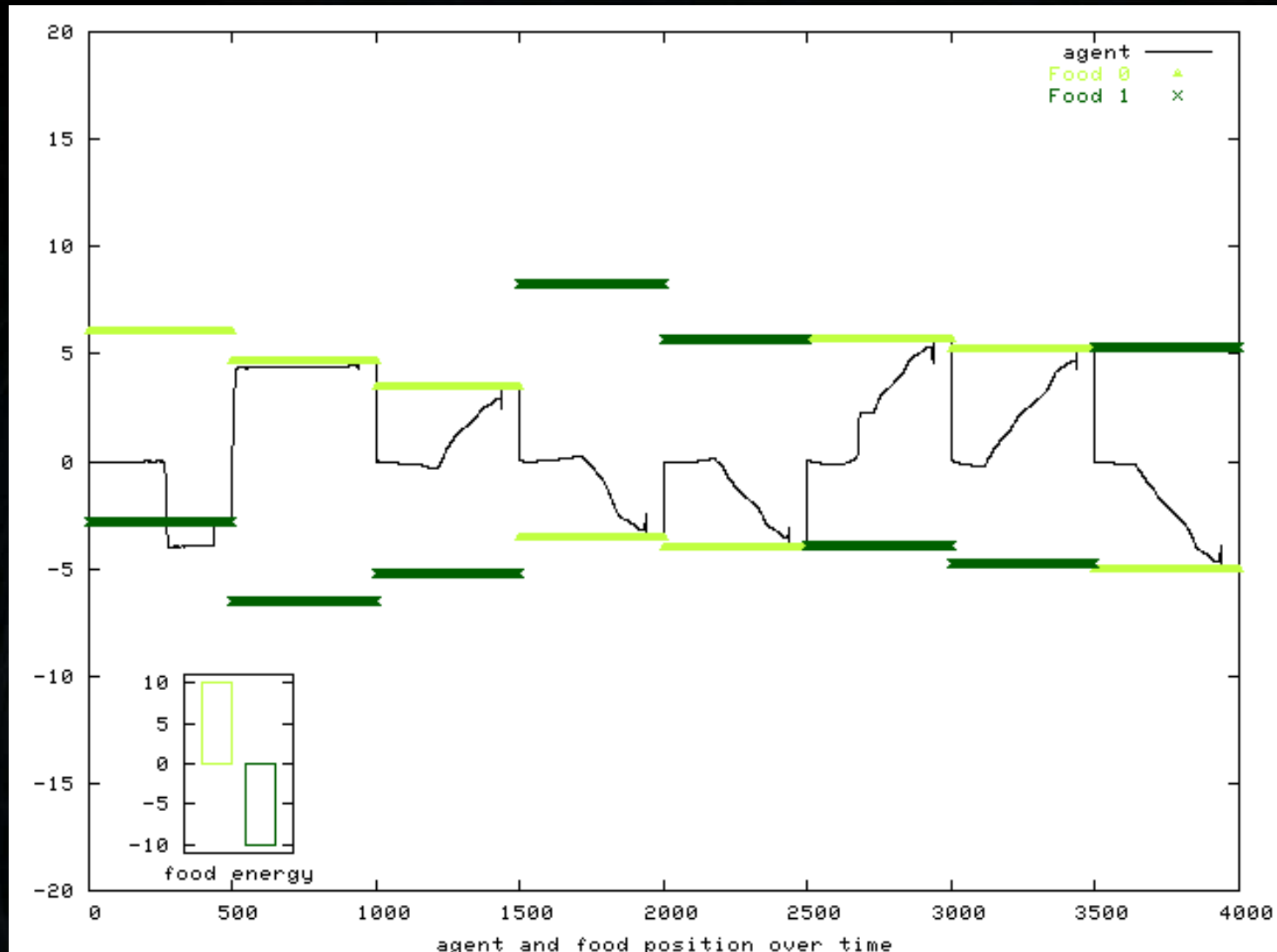




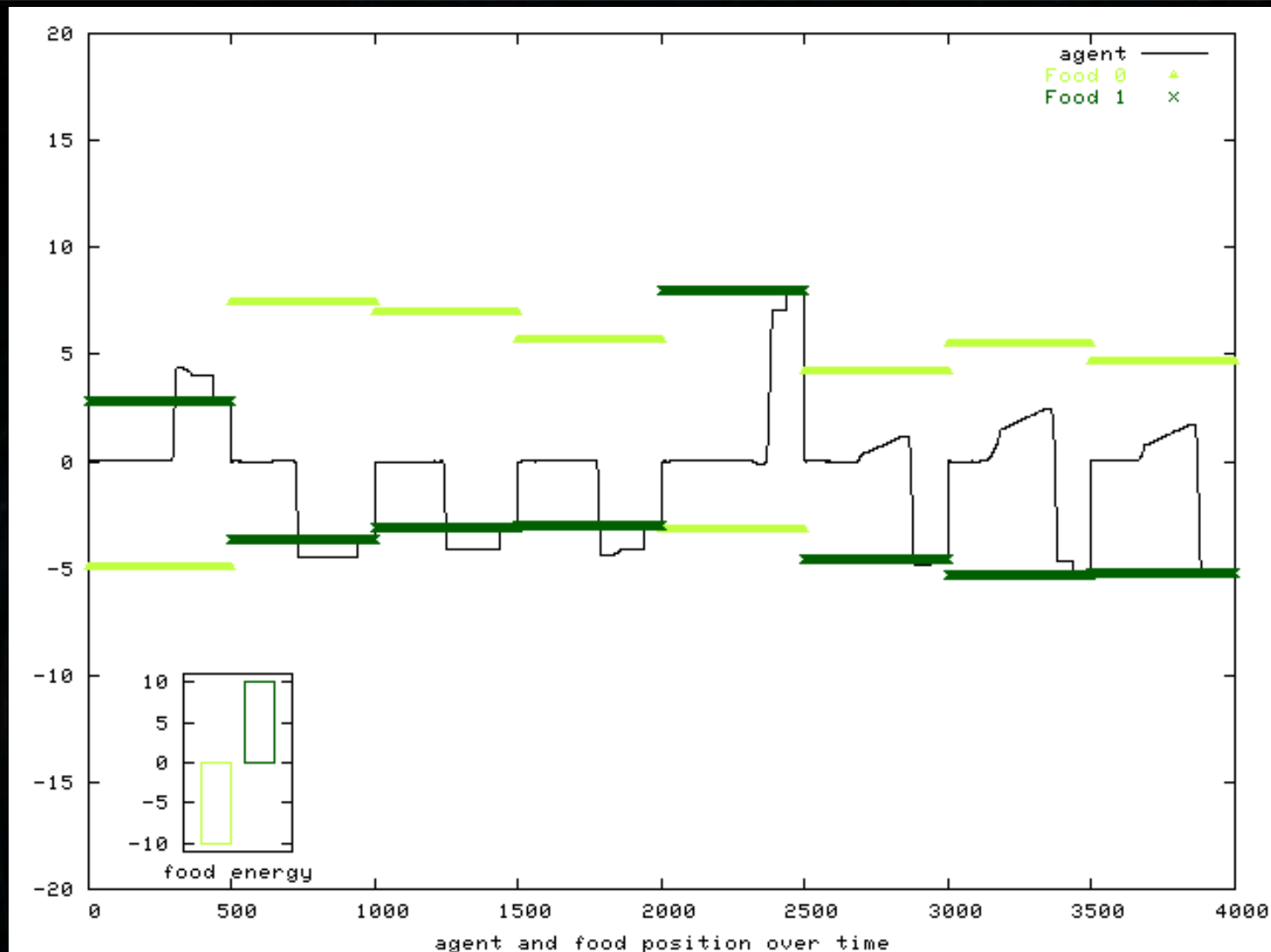
## Results so far

- ◆ Risk aversion
- ◆ Behaviour energy-stability matching
- ◆ Learning with TC
- ◆ Learning with synaptic plasticity

# Learning with time constants (condition 0)

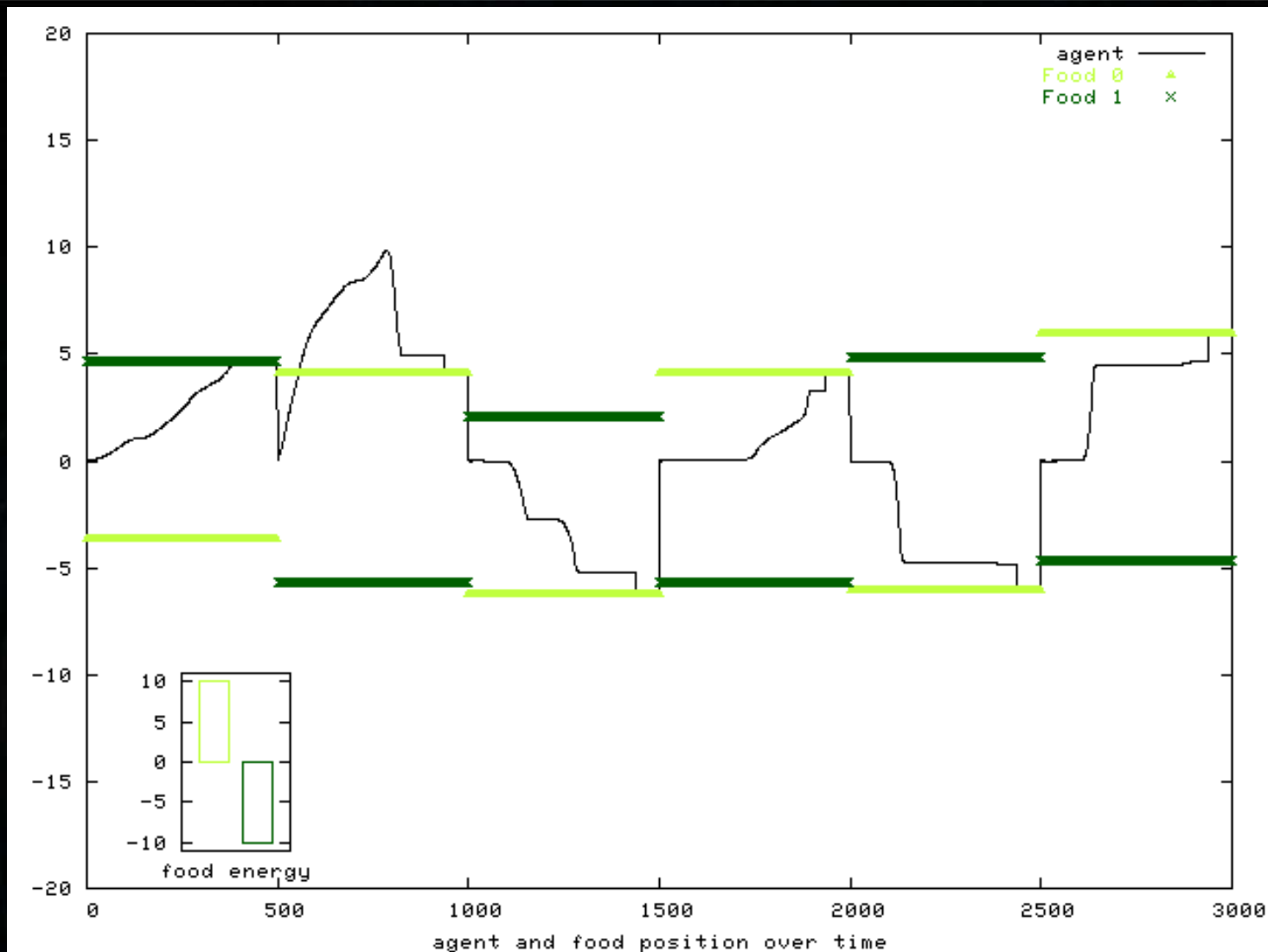


# Learning with time constants (condition 1)

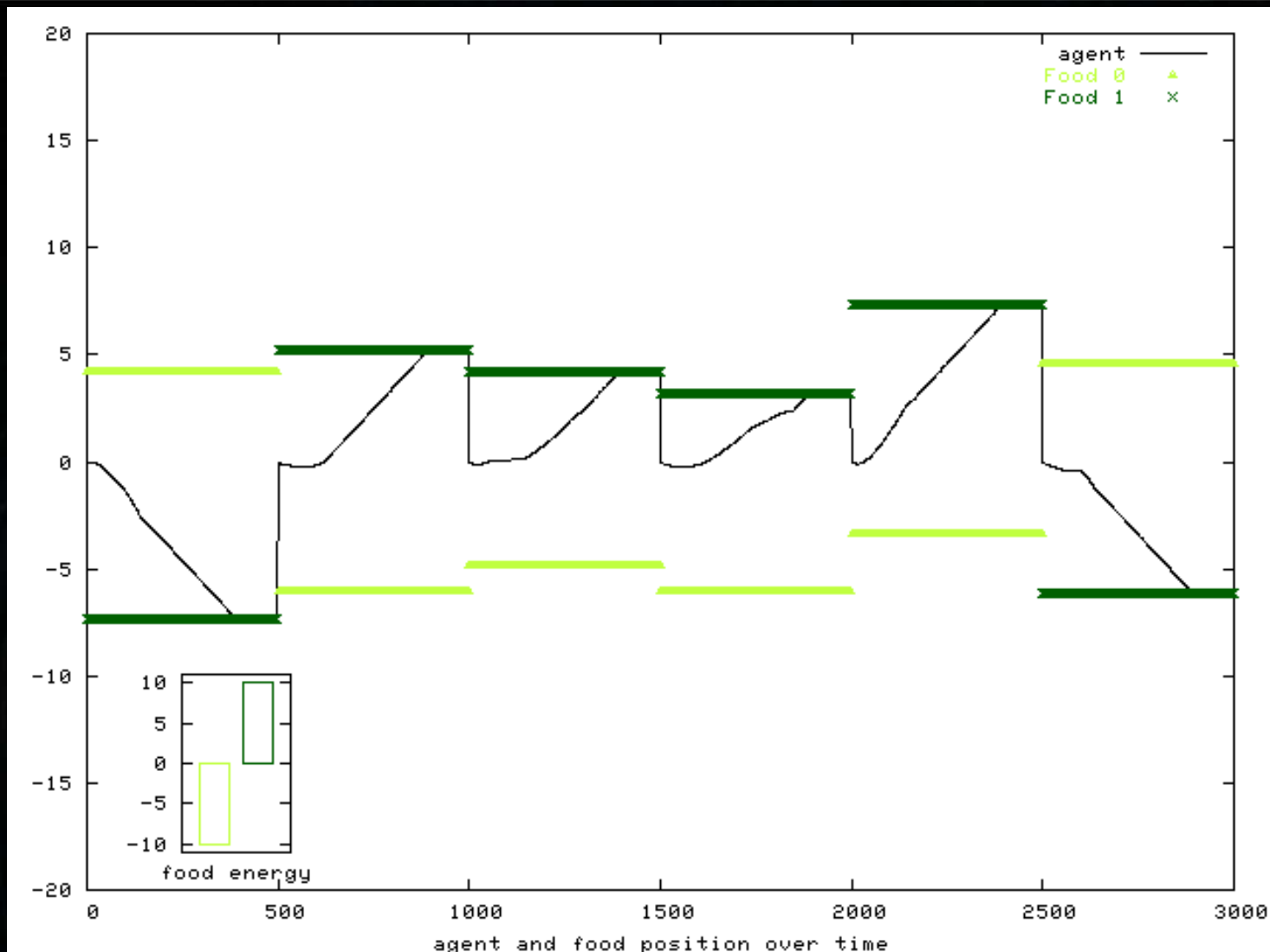




# Learning with synaptic plasticity (condition 0)



# Learning with synaptic plasticity (condition 1)



**THANK YOU !!!**

*(so... are plants cognitive?)*